LEONID GREMYACHIKH

@ lgremyachikh@gmail.com github.com/bamasa

♀ Moscow, Russia ★ gitlab.com/bamasa

% bamasa.github.io Google Scholar: NVO2imsAAAAJ



EDUCATION

HSE University

Computer and Information Sciences

Mov 2019 - Oct 2022

Moscow, Russia

- PhD in Applied Mathematics and Informatics
- PhD candidate

HSE University

Data Science

Sep 2016 - Jun 2018

- ♥ Moscow, Russia
- MS in Applied Mathematics and Informatics
- Grade in Reinforcement Learning = 10
- Grade in Deep Learning = 10
- Thesis theme: "Automation of Satellite Collision Avoidance Maneuvers with Deep Reinforcement Learning"

National Research University Moscow Aviation Institute

Design and Technology of Electronic Equipment

₩ Sep 2009 - Feb 2015

♥ Moscow, Russia

• Specialist in Engineering

EDUCATION/COURSES

Computer Vision OTUS (2020)

Autumn School on Generative Models

HSE-Yandex (26-29 November 2019)

HARD SKILLS

- Deep Learning
- Computer Vision
- Machine Learning
- Reinforcement Learning
- MLOps

Python

C++



SOFT SKILLS

- presentation skills
- meeting management skills
- communication
- self-management, self-efficiency
- teamwork skills
- mentoring
- documentation

WORK EXPERIENCE

FBS Data Scientist Sep 2022 - currently Moscow, Russia Fraud Detection. Python ML Research **MLOps** Laboratory of Methods for Big Data Analysis **Research Assistant** Apr 2018 - currently ♥ Moscow, Russia ML research in different fields of physics, scientific publications, students, online courses. Python ML Research Physics **Papers MLOps** Teaching **TensorLab** Head of R&D Mov 2021 - Oct 2022 Moscow, Russia Calculating maneuvers and refining spacecraft position predictions. Python Management ML Research **Physics MLOps ADALISK Senior Machine Learning Engineer Aug** 2021 - Sep 2022 ♥ Moscow, Russia Computer vision for planning tooth correction. DL **Computer Vision** Python ML Research **MLOps** Radio Engineering Institute named after academician A. L. Mints **Engineer Apr** 2015 - Apr 2018 ♥ Moscow, Russia Digital signal processing, Signal Analysis, Space Objects Recognition. Mathcad C++

PROJECTS

Fraud Detection (2022)

• Real-time detection of frauders in time series

Python ML

Satellite Collision Avoidance Maneuvers (2021-2022)

- maneuvers calculation
- refining position predictions
- web service
- management

Python Management

Computer Vision for working with teeth (2021-2022)

· 3D segmentation and different tasks

Python DL CV

Reinforcement Learning for Poker (2021)

• RL: environment, simulator, algorithms, experiments, research

Python RL

Reinforcement Learning for automatic budget management for advertising campaigns. (2021)

- RL: environment, simulator, algorithms, experiments, research
- Management

Python RL Management

Anomaly Prediction in Storage Area Network (2018-2021)

- <u>a publication</u> "SANgo: a storage infrastructure simulator with reinforcement learning support"
- researched methods for improving Digital Twin of Storage Area Network, tested methods on chaotic systems, developed OpenAI Gym wrappers, applied RL methods
- NLP on logs

Python Docker DL RL NLP

Sixth Machine Learning in High Energy Physics Summer School (2020)

Volunteering, helping students.

Python DL Mentoring

International Data Analysis Olympiad (2020)

Participated in the preparation of Higher School of Economics and Yandex the 3rd international data analysts olympiad. The competition task – build a model that would predict the position of space objects using simulation data.

- analyzed the task and SOTA
- prepared and verified data (ephemeris) using GMAT and SGP4
- prepared a baseline (LR)
- checked and analyzed the solutions of the participants
- answered questions from participants

Python GMAT

Satellite Positioning (2019-2020)

The project task – build a model that would predict the position of space objects using simulation data.

• students mentoring

Python Management Mentoring

Distributed Deep Learning (2018-2019)

• developed Distributed Deep Learning pipelines

Python Docker Azure DL

Model Gym (2018)

developed and debugged a hyperparameter optimization system

Python ML

Automation of Satellite Collision Avoidance Maneuvers with Deep Reinforcement Learning (2017-2018)

- a publication "Space Navigator: a Tool for the Optimization of Collision Avoidance Maneuvers"
- researched and developed a system for calculating maneuvers for spacecraft based on Machine Learning
- MVP is done
- participated in IAA SciTech Forum 2018

Python DL RL

Sex Prediction via Deep Learning (2017)

- researched Sex Prediction via Deep Learning by person's Friends Graph from social network and friends' photos
- used pre-trained VGG from ImageNet, Social Network Analysis
- collected data from "vk.com"
- obtained better score than the baseline

Python DL Social Network Analysis

PUBLICATIONS

• 🖹 Journal Articles

- Arzymatov, Kenenbek, Mikhail Hushchyn, Andrey Sapronov, Vladislav Belavin, Leonid Gremyachikh, Maksim Karpov, and Andrey Ustyuzhanin (2021). "Online detection of failures generated by storage simulator". In: *Journal of Physics: Conference Series* 1740, p. 012052.
- K. Arzymatov, A. Sapronov, V. Belavin, L. Gremyachikh, M. Karpov, A. Ustyuzhanin, I. Tchoub, and A. Ikoev (2020). "SANgo: a storage infrastructure simulator with reinforcement learning support". In: *PeerJ Computer Science*, pp. 1–16.
- "Space Navigator: a Tool for the Optimization of Collision Avoidance Maneuvers" (2020). In: Advances in the Astronautical Sciences 170, pp. 305–319. eprint: 1902.02095.

CONFERENCES & SPEECHES

- <u>SMILES</u>, Moscow, SKOLTECH, international summer school poster presentation "Al and Satellite Problems" (2020)
- <u>IDAO</u> (International Data Analysts Olympiad) IDAO Webinar on Data Analysis for Satellite Tracking (2020), <u>webinar</u>
- Space debris: fundamental and practical aspects of the threat, Moscow, Institute of Astronomy RAS and Space Research Institute RAS, Russian conference with international participation – report "Space Navigator" (2019)
- IAA SciTech Forum 2018, Moscow, RUDN, international conference paper report "SpaceNavigator: a Tool for the Optimization of Collision Avoidance Maneuvers" (2018)

ART PROJECTS

• For All Exists Infinity – VR installation created with the Unreal Engine (2021, exhibition "Game Junction").

TEACHING

- Online course "Machine Intelligence, interdisciplinary perspective", HSE University, 2021-2022
- Seminars "Introduction to Data Analysis", HSE University, 2021
- Online course "Python for Data Science", Skillbox, 2020-2021